

Problem 1

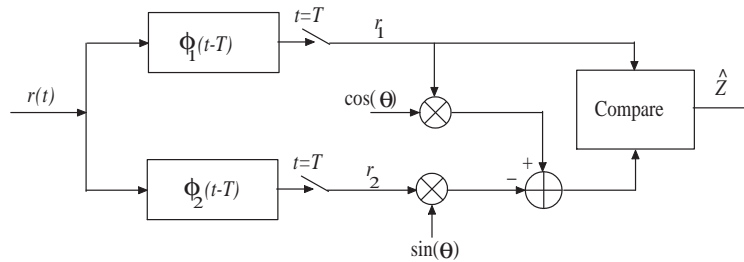
1. An O.N. spanning set for the signal set is given by

$$\phi_1(t) = \sqrt{\frac{2}{T}} \cos(2\pi f_0 t), \quad \text{and} \quad \phi_2(t) = \sqrt{\frac{2}{T}} \sin(2\pi f_0 t), \quad 0 \leq t \leq T$$

Then $s_0(t) = \sqrt{E}\phi_1(t)$ and thus $\mathbf{s}_0 = (\sqrt{E}, 0)$. Also since

$$s_1(t) = \sqrt{E} \cos(\theta)\phi_1(t) - \sqrt{E} \sin(\theta)\phi_2(t)$$

we have $\mathbf{s}_1 = (\sqrt{E} \cos(\theta), \sqrt{E} \sin(\theta))$. A block diagram of the optimal receiver is shown below.



Note that we have ignored the term \sqrt{E} in the multipliers.

2. We have $P(E) = Q\left(\frac{d}{\sqrt{2N_0}}\right)$, where

$$d^2 = \|\mathbf{s}_1 - \mathbf{s}_0\|^2 = [\sqrt{E} - \sqrt{E} \cos(\theta)]^2 + [\sqrt{E} \sin(\theta)]^2 = 2E[1 - \cos(\theta)]$$

To minimize $P(E)$ we need to maximize d . From the above we see that d is maximized for $\theta = \pi$ which results in $d^2 = 4E$. For this value of θ the signal set is BPSK. We need $\frac{E_b}{N_0} \geq 9.6\text{dB}$ and $W \geq R_b$.

Problem 2

1. $\frac{E_b}{N_0} = \frac{P}{RN_0} = \frac{150,000}{5,000} = 30$. Thus $10 \log \frac{E_b}{N_0} = 14.7$ dB. Thus the available SNR is 14.77 dB. The available $R/W = \frac{5,000}{2\alpha} = 5/8$. Our system must require $\frac{E_b}{N_0} \leq 14.7$ dB and must have $R_b/W \geq 5/8$. The simplest system with these requirements is BPSK.

$$s_0(t) = \sqrt{\frac{2E}{T}} \cos(2\pi f_0 t), \quad s_1(t) = \sqrt{\frac{2E}{T}} \cos(2\pi f_0 t + \pi), \quad 0 \leq t \leq T$$

where $E = E_b = 30N_0$ and $T = T_b = 1/R = .2$ msec.

2. $\frac{E_b}{N_0} = \frac{P}{RN_0} = \frac{1,250,000}{5,000} = 250$. Thus $10\log \frac{E_b}{N_0} \approx 24$ dB. Thus the available SNR is 24 dB. The available $R/W = \frac{5,000}{2\alpha} = 4.54$. Our system must require $\frac{E_b}{N_0} \leq 24$ dB and must have $R_b/W \geq 4.54$. The simplest system with these requirements is 32PSK.

$$s_i(t) = \sqrt{\frac{2E}{T}} \cos\left(2\pi f_0 t + \frac{2\pi(i-1)}{32}\right), \quad i = 1, 2, \dots, 32, \quad 0 \leq t \leq T$$

where $E = E_b \log_2 32 = 5E_b = 5 \times 250N_0 = 1250N_0$ and $T = T_b \log_2 32 = 5T_b = 5/R = 1$ msec.

3. $\frac{E_b}{N_0} = \frac{P}{RN_0} = \frac{320,000}{5,000} = 64$. Thus $10\log \frac{E_b}{N_0} \approx 18.06$ dB. Thus the available SNR is 18.06 dB. The available $R/W = \frac{5,000}{2\alpha} = 2.94$. Our system must require $\frac{E_b}{N_0} \leq 18.06$ dB and must have $R_b/W \geq 2.94$. The simplest system with these requirements is 8ASK.

$$s_i(t) = a_i \sqrt{\frac{2}{T}} \cos(2\pi f_0 t), \quad i = 1, 2, \dots, 8, \quad 0 \leq t \leq T$$

where

$$a_i \in \left\{ \pm \frac{7A}{2}, \pm \frac{5A}{2}, \pm \frac{3A}{2}, \pm \frac{A}{2} \right\}$$

With this selection

$$E_{\text{ave}} = \frac{1}{8} \times 2 \times \left[\frac{49A^2}{4} + \frac{25A^2}{4} + \frac{9A^2}{4} + \frac{A^2}{4} \right] = \frac{21A^2}{4}$$

Now $E_{\text{ave}} = E_b \log_2 8 = 3E_b = 192N_0$. Thus

$$A \sqrt{\frac{4E_{\text{ave}}}{21}} = 16 \sqrt{\frac{N_0}{7}}$$

Also $T = T_b \log_2 8 = 3T_b = 3/R = .6$ msec.

Problem 3

1. We have $W = 2.25 - 2 = .25$ MHz. Therefore, $R_b/W = 4$ bits/sec/Hz. The system we choose must have $R_b/W \geq 4$.

- (a) We can use q -ary PSK for $q \geq 16$. 16PSK has the smallest power requirement for which $\frac{E_b}{N_0} = 17.4$ dB or 55. Thus

$$\frac{E_b}{N_0} = \frac{P}{R_b N_0} = 55, \quad \implies P = 55 \times R_b \times N_0 = 110 \text{ W}$$

- (b) No FSK system can provide $R_b/W \geq 4$.

- (c) We can use q -ary ASK for $q \geq 16$. 16ASK has the smallest power requirement for which $\frac{E_b}{N_0} = 23.2$ dB or 207. Thus $P = 207 \times R_b \times N_0 = 414 \text{ W}$.

(d) Again we can use 16QASK which requires $\frac{E_b}{N_0} = 13.2$ dB or 20.9. Thus $P = 20.9 \times R_b \times N_0 = 41.8$ W.

(e)

$$\frac{E_b}{N_0} = \frac{2^{R_b/W} - 1}{R_b/W} = \frac{2^4 - 1}{4} = 3.75$$

Thus

$$P = 3.75 \times R_b \times N_0 = 7.5W$$

2. $R_b = 125$ Kbits/s. Then $R_b/W = .5$ bits/sec/Hz. The system we choose must have $R_b/W \geq .5$.

(a) Any PSK system can be used. For BPSK or QPSK we get the smallest P . $\frac{E_b}{N_0} = 9.6$ dB or 9.12. Thus

$$\frac{E_b}{N_0} = \frac{P}{R_b N_0} = 9.12, \implies P = 9.12 \times R_b \times N_0 = 2.28 W$$

(b) Any FSK system can be used. For 8FSK we get the smallest P . $\frac{E_b}{N_0} = 7$. Thus

$$\frac{E_b}{N_0} = \frac{P}{R_b N_0} = 7, \implies P = 7/4 = 1.75 W$$

(c) Any ASK system can be used. For BASK we get the smallest P . $\frac{E_b}{N_0} = 9.12$. Thus

$$\frac{P}{R_b N_0} = 9.12, \implies P = 2.28 W$$

(d)

$$\frac{E_b}{N_0} = \frac{2^{R_b/W} - 1}{R_b/W} = \frac{2^{.5} - 1}{.5} = .828$$

Thus

$$P = .207W$$

Problem 4

1. There are 8 signals in the signal set. Thus $T = T_b \log_2 8 = 3/R_b = 3\text{msec}$.

2.

$$\int_0^T \{A \cos[2\pi f_0 t + \theta]\}^2 dt = \frac{A^2 T}{2}$$

Thus

$$E_{\text{ave}} = \frac{1}{8} \left\{ 4 \times \frac{a^2 T}{2} + 4 \times \frac{(3a)^2 T}{2} \right\} = 2.5a^2 T$$

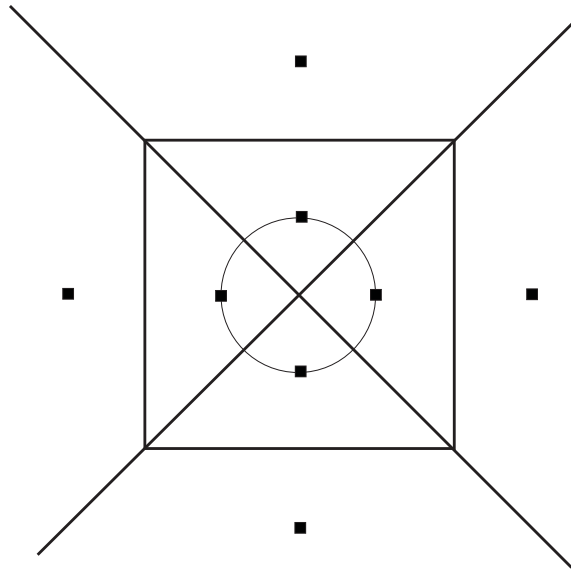
3. The following is a basis for the signal set.

$$\phi_1(t) = \sqrt{\frac{2}{T}} \cos(2\pi f_0 t), \quad \phi_2(t) = \sqrt{\frac{2}{T}} \sin(2\pi f_0 t), \quad 0 \leq t \leq T$$

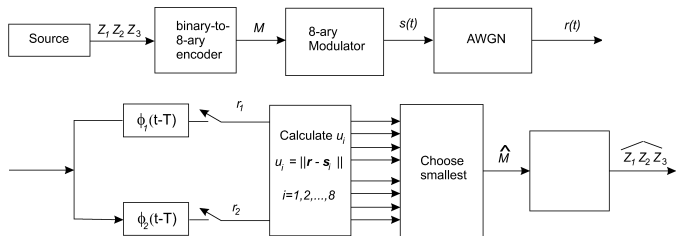
The signals are then given by

$$\begin{aligned} s(t) &= A \cos(\theta) \cos(2\pi f_0 t) - A \sin(\theta) \sin(2\pi f_0 t) \\ &= A \sqrt{\frac{T}{2}} \cos(\theta) \phi_1(t) - A \sqrt{\frac{T}{2}} \sin(\theta) \phi_2(t) \end{aligned}$$

for which $\mathbf{s} = (A \sqrt{\frac{T}{2}} \cos(\theta), A \sqrt{\frac{T}{2}} \sin(\theta))$. The vector representation and the decision regions are plotted below.



4. The transmitter and receiver block diagrams are shown below.



5. Using the union bound we get

$$P(E) \leq \frac{1}{8} \sum_{i=1}^8 \sum_{j \neq i} Q \left(\frac{d_{ij}}{\sqrt{2N_0}} \right) \leq 7Q \left(\frac{d_{\min}}{\sqrt{2N_0}} \right) = 7Q \left(\sqrt{\frac{a^2}{N_0}} \right)$$

since $d_{\min} = a\sqrt{2}$.

Problem 5

1. Let $y(t)$ denote the output of the filter. Then $R = y(T)$ and

$$\begin{aligned} y(t) = r(t) * h(t) &= \int_0^t r(\tau) h(t - \tau) d\tau \\ &= \int_0^t s(\tau) e^{-a(t-\tau)} d\tau + \int_0^t N_W(\tau) e^{-a(t-\tau)} d\tau \end{aligned}$$

Then

$$R = y(T) = e^{-aT} \int_0^T s(\tau) e^{a\tau} d\tau + N = s + N$$

where

$$N = e^{-aT} \int_0^T N_W(\tau) e^{a\tau} d\tau$$

For $s_0(t)$ we have $s = 0$ and for $s_1(t)$ we get $s = \frac{1}{a} \sqrt{\frac{E}{T}} (1 - e^{-aT})$. N is Gaussian and we need to find its mean and variance. Now $E(N) = 0$ and

$$\begin{aligned} E[N^2] &= e^{-2aT} \int_0^T \int_0^T E[N_W(\tau_1) N_W(\tau_2)] e^{a\tau_1} e^{a\tau_2} d\tau_1 d\tau_2 \\ &= e^{-2aT} \int_0^T \int_0^T N_0/2 \delta(\tau_1 - \tau_2) e^{a\tau_1} e^{a\tau_2} d\tau_1 d\tau_2 \\ &= e^{-2aT} N_0/2 \int_0^T e^{2a\tau_1} d\tau_1 = \frac{N_0}{4a} [1 - e^{-2aT}] \end{aligned}$$

Therefore $\sigma_N^2 = \frac{N_0}{4a} [1 - e^{-2aT}]$. Now $P(E) = Q \left(\frac{d}{2\sigma_N} \right)$. Thus

$$P(E) = Q \left[\frac{\sqrt{E}(1 - e^{-aT})}{\sqrt{aTN_0(1 - e^{-2aT})}} \right]$$

2. We need to maximize the argument of the Q function above. Let

$$f(a) = \frac{\sqrt{E}(1 - e^{-aT})}{\sqrt{aTN_0(1 - e^{-2aT})}}$$

Taking the derivative of $f(a)$ with respect to a we see that $a = 0$ sets the derivative to zero.
For $a = 0$

$$h(t) = \begin{cases} 1 & 0 \leq t \\ 0 & \text{otherwise.} \end{cases}$$

But since we sample at $t = T$, this is the same as

$$h(t) = \begin{cases} 1 & 0 \leq t \leq T \\ 0 & \text{otherwise.} \end{cases}$$

which is the matched filter. No surprize.

3. For the optimal matched filter receiver we have

$$P(E) = Q\left(\sqrt{\frac{ET}{2N_0}}\right)$$