

Problem 2

1. Let the transmitted signal be given by

$$s(t) = A_c m(t) \cos(2\pi f_c t)$$

On the receiver side, the output of the product modulator in the coherent detector is then given by

$$\begin{aligned} r(t) &= A_c A_r m(t) \cos(2\pi f_c t) \cos(2\pi f_c t + \phi) \\ &= \frac{A_c A_r}{2} m(t) [\cos \phi + \cos(4\pi f_c t + \phi)] \end{aligned}$$

Upon low-pass filtering the signal $r(t)$, we get the final output of the Coherent detector, namely

$$v(t) = \frac{A_c A_r}{2} m(t) \cos \phi$$

If ϕ is constant, then $v(t) = am(t)$ where $a = \frac{A_c A_r}{2} \cos \phi$. The demodulated waveform only differs from the message $m(t)$ by a constant factor (attenuation or amplification).

Note that if $\phi = \frac{\pi}{2}$, then $v(t) = 0$, which, of course, is undesirable. If $\pi < \phi < 2\pi$, then $v(t)$ has a different sign from $m(t)$, e.g., $v(t) = -m(t)$. For audio signals, this is OK, since we hear $m(t)$ and $-m(t)$ the same. But for video signals, this needs to be corrected.

If ϕ varies with time, see answer to part (b).

2. We proceed along similar lines to part (a). In this case, $r(t)$ is given by

$$\begin{aligned} r(t) &= A_c A_r m(t) \cos(2\pi f_c t) \cos[2\pi(f_c + \Delta f)t] \\ &= \frac{A_c A_r}{2} m(t) [\cos(2\pi \Delta f t) + \cos(2\pi(2f_c + \Delta f)t)] \end{aligned}$$

Upon low-pass filtering the signal $r(t)$, the final output of the coherent detector, $v(t)$, is then given by

$$v(t) = \frac{A_c A_r}{2} m(t) \cos(2\pi \Delta f t)$$

Assuming that $\Delta f \neq 0$ is small, the amplitude of the received waveform *slowly* fluctuates, due to a *residual modulation* of the demodulated signal $v(t)$ at the frequency Δf . This is clearly undesirable and should be corrected. However, if $\Delta f = 0$, then $v(t) = r(t)$ and we get the required message signal, $m(t)$.

Problem 3

We have $f_c = 105\text{MHz}$, $A_m = 5\text{V}$, $f_m = 15\text{kHz}$, $k_f = 10\text{kHz/V}$

1. We have $\Delta f = k_f A_m = 50\text{ KHz}$. By Carson's rule,

$$B_T \approx 2\Delta f + 2f_m = 130\text{ KHz}$$

2. $\beta = \frac{\Delta f}{f_m} = \frac{50}{15} \approx 3.33$ radians. From the universal curve,

$$B_T/\Delta f|_{\beta=3.33} \approx 3.5.$$

This yields $B_T \approx 3.5\Delta f = 175\text{ KHz}$.

3. Here $A'_m = 2A_m = 10\text{V}$. Hence, $\Delta f' = k_f A'_m = 100\text{kHz}$. By Carson's rule,

$$B_T \approx 2\Delta f' + 2f_m = 230\text{ KHz}.$$

We have $\beta = \frac{100}{15} \approx 6.67$ radians. From the universal curve,

$$B_T \approx 3\Delta f' = 300\text{ KHz}.$$

4. In this case, $f'_m = 2f_m = 30\text{ KHz}$. By Carson's rule,

$$B_T \approx 2\Delta f + 2f'_m = 160\text{ KHz}.$$

Also in this case, $\beta = \frac{50}{30} \approx 1.67$ radians. From the universal curve, we get

$$B_T \approx 5\Delta f = 5(50) = 250\text{ KHz}.$$

Problem 1

1. (a)

(b)

The lowest frequency is $f = 5$ KHz.

2. (a)

(b)

In this case the lowest frequency to guarantee that the message can be demodulated is given by $f = 10$ KHz.







