Problem 1: The code below executes on a dynamically scheduled four-way superscalar DLX implementation that uses reorder buffer entry numbers to name destination registers.

- Loads and stores use the load/store unit, which consists of segments L1 and L2.
- The floating-point multiply unit is fully pipelined and consists of six segments.
- The usual number of instructions (for a 4-way superscalar machine) can be fetched, decoded, and committed per cycle.
- An unlimited number of instructions can complete per cycle. (This makes the solution easier.)
- There are an unlimited number of reservation stations and reorder buffer entries.
- The target of a branch is fetched in the cycle after the branch is in ID, whether or not the branch condition is available. (We'll cover that later.)
- (a) Show a pipeline execution diagram for the code below until the beginning of the fourth iteration. Show where instructions commit.
- (b) What is the CPI for a large number of iterations? Hint: There should be less than six cycles per iteration.
- (c) Show the entries in the register map for registers f0 and r1 for each cycle. (Make up reorder buffer entry numbers.)

```
LOOP: ! LOOP = 0x1000

ld f0, 0(r1)

muld f0, f0, f2

sw 0(r1), f0

addi r1, r1, #8

sub r2, r1, r3

bnez r2, LOOP
```

(d) The first two instructions of the code below are different than the code above, the other instructions are identical. It runs on a system identical to the one above except that there are only 1000 reorder buffer entries. (That's actually a lot, but it's not unlimited.) What is the CPI for a large number of iterations? Is the CPI really lower in the period before reorder buffers are used up? If you can, solve the problem without drawing a complete pipeline execution diagram.

```
LOOP: ! LOOP = 0x1000
ld f4, 0(r1)
muld f0, f0, f4
sw 0(r1), f0
addi r1, r1, #8
sub r2, r1, r3
bnez r2, LOOP
```

Problem 2: When the MIPS program below starts register \$t0 holds the address of a string, the program converts the string to upper case.

(For MIPS documentation see http://www.ece.lsu.edu/ee4720/mips32v1.pdf and http://www.ece.lsu.edu/ee4720/mips32v2.pdf. Here are the relevant differences with DLX: branches and jumps are delayed (1 cycle). Some branch instructions compare two registers. Register \$0 works like DLX r0.)

LOOP:

```
lbu $t1, 0($t0)
addi $t0, $t0, 1
beq $t1, $0, DONE
slti $t2, $t1, 97 # < 'a'
bne $t2, $0 LOOP
slti $t2, $t1, 123 # 'z' + 1
beq $t2, $0, LOOP
addi $t1, $t1, -32
j LOOP
sb $t1,-1($t0)</pre>
```

DONE:

Convert the program to IA-64 assembly language using predicated instructions. (You're not expected to know it at this point.) IA-64 is described in the IA-64 Application Developer's Architecture Guide, available at http://www.ece.lsu.edu/ee4720/ia-64.pdf.

For this problem one can ignore alot of IA-64's features. Here is what you will need to know: IA-64 has 64 1-bit predicate registers, p0 to p63, which are written by cmp (compare) and other instructions. Predicates can be specified for most instructions, including cmp itself. See 11.2.2 for a description of how to use IA-64 predicates.

To solve the problem look at the following sections: 9.3, 9.3.1, and 9.3.2 (a brief description of where to place stops); 11.2.2 (predicate description and some more information on stops); and Chapter 7 (for instruction descriptions). The following instructions will be needed: cmp (compare, look at the normal [none] and and comparison types), br (branch), load, store, and add.

- Use general-purpose registers r0-r31 and predicate registers p1-p63 in your solution. (There are 128 general-purpose registers, but those above r31 must be allocated.)
- Minimize the number of instructions per iteration assuming about half the characters are lower case.
- Use predicates to eliminate some branches.
- Make use of post-increment loads or stores.
- Pay attention to data type sizes.
- Show stops but do not show bundle boundaries.