

# EE 7630: Detection and Estimation Theory

Homework Two (& Quiz Two), Spring of 2007

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Due at 5:40 pm, Wednesday, March 28, 2007

1. Let

$$r_i = a + n_i, i = 1, 2, \dots, N,$$

where  $r_i$  is the  $i$ th observation sample,  $a$  is the unknown nonrandom parameter to be estimated and  $n_i$  is the  $i$ th additive noise sample. We assume that  $n_i$  are each independent Gaussian variables,  $N(0, \sigma_n)$ .

- (a) Derive the *a priori* density function  $f_{\vec{R}|A}(\vec{r}|a)$  in terms of  $\sigma_n$ ,  $a$  and  $r_i$ .
- (b) Obtain the maximum-likelihood estimate  $\hat{a}_{ml}(\vec{r})$  according to (a).
- (c) Is the estimate  $\hat{a}_{ml}(\vec{r})$  in (b) biased or unbiased? Justify it.
- (d) Calculate the Cramer-Rao lower bound for all the unbiased estimates  $\hat{a}(\vec{r})$ .
- (e) We construct a different estimator from  $\hat{a}_{ml}(\vec{r})$  in (b) such that

$$\hat{a}'(\vec{r}) \equiv r_1.$$

First justify whether  $\hat{a}'(\vec{r})$  is unbiased or not. Is this estimator more efficient than the estimator  $\hat{a}_{ml}(\vec{r})$  in (b)?

2. Let

$$r_i = a + n_i, i = 1, 2, \dots, N,$$

where  $r_i$  is the  $i$ th observation sample,  $a$  is the unknown parameter to be estimated and  $n_i$  is the  $i$ th additive noise sample. We assume that  $a$  is Gaussian,  $N(0, \sigma_a)$ , and that  $n_i$  are each independent Gaussian variables,  $N(0, \sigma_n)$ .

- (a) Derive the *a priori* density function  $f_{\vec{R}|A}(\vec{r}|a)$  in terms of  $\sigma_n$ ,  $\sigma_a$ ,  $a$  and  $r_i$ .
- (b) Derive the *a posteriori* density function  $f_{A|\vec{R}}(a|\vec{r})$  in terms of  $\sigma_n$ ,  $\sigma_a$ ,  $a$  and  $r_i$ .
- (c) Determine the maximum *a posteriori* estimate  $\hat{a}_{MAP}(\vec{r})$ .
- (d) Is the estimate  $\hat{a}_{MAP}(\vec{r})$  in (c) biased or unbiased? Justify it.
- (e) Calculate the Cramer-Rao lower bound for all the unbiased estimates  $\hat{a}(\vec{r})$ .