

# Automatic Performance Tuning and Analysis of Sparse Triangular Solve

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June 22, 2002

Berkeley Benchmarking and OPtimization (BeBOP) Project

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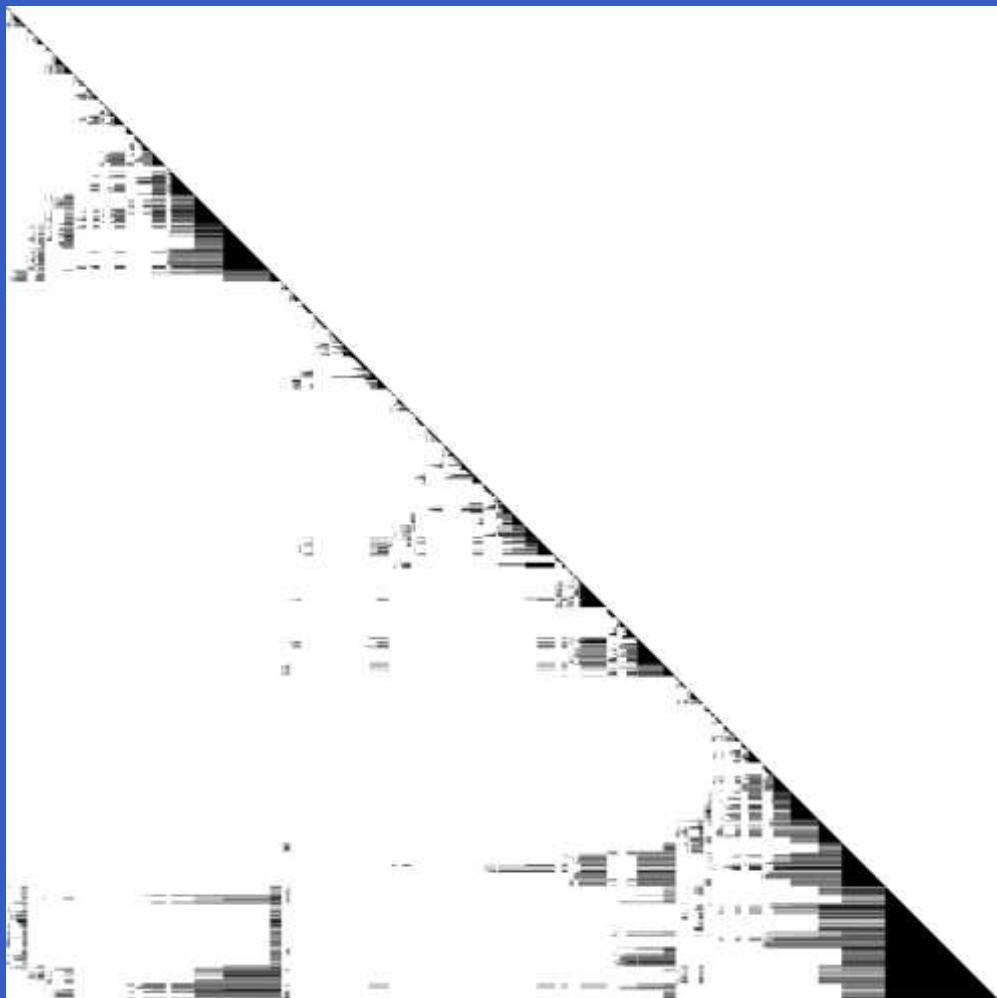
# Context: High-Performance Libraries

- Application performance dominated by a few *computational kernels*
  - Solving PDEs (linear algebra ops)
  - Google (sparse matrix-vector multiply)
  - Multimedia (signal processing)
- Performance tuning today
  - Vendor-tuned standardized libraries (e.g., BLAS)
  - User tunes by hand
- Automated tuning for dense linear algebra, FFTs, . . .
  - PHiPAC/ATLAS (dense linear algebra)
  - FFTW/SPIRAL/UHFFT (signal processing)

# Problem Area: Sparse Matrix Kernels

- Performance issues in sparse linear algebra
  - High bandwidth requirements and poor instruction mix
  - Depends on architecture, kernel, and *matrix*
  - How to select data structures, algorithms? at run-time?
- Approach to automatic tuning: for each kernel,
  - *Identify* and *generate* a space of implementations
  - *Search* (models, experiments) to find the fastest one
- Early success: SPARSITY (Im & Yelick '99) for sparse matrix-vector multiply ( $\text{SpM} \times \text{V}$ )
- This talk: *Sparse triangular solve* (SpTS), arising in sparse Cholesky and LU factorization (uniprocessor)

# Sparse Triangular Matrix Example



- raetsky4  
(structural problem)  
+ SuperLU 2.0 +  
colmmd
- Dimension: 19779
- No. non-zeros:  
12.6 M
- Dense trailing  
triangle:  
dim=2268  
20% of total nnz

# Idea: Sparse/Dense Partitioning

Partition the matrix into sparse ( $L_1, L_2$ ) and dense ( $L_D$ ) parts:

$$\begin{pmatrix} L_1 & \\ L_2 & L_D \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

Leads to 1 SpTS, 1 SpM×V, and 1 Dense TS:

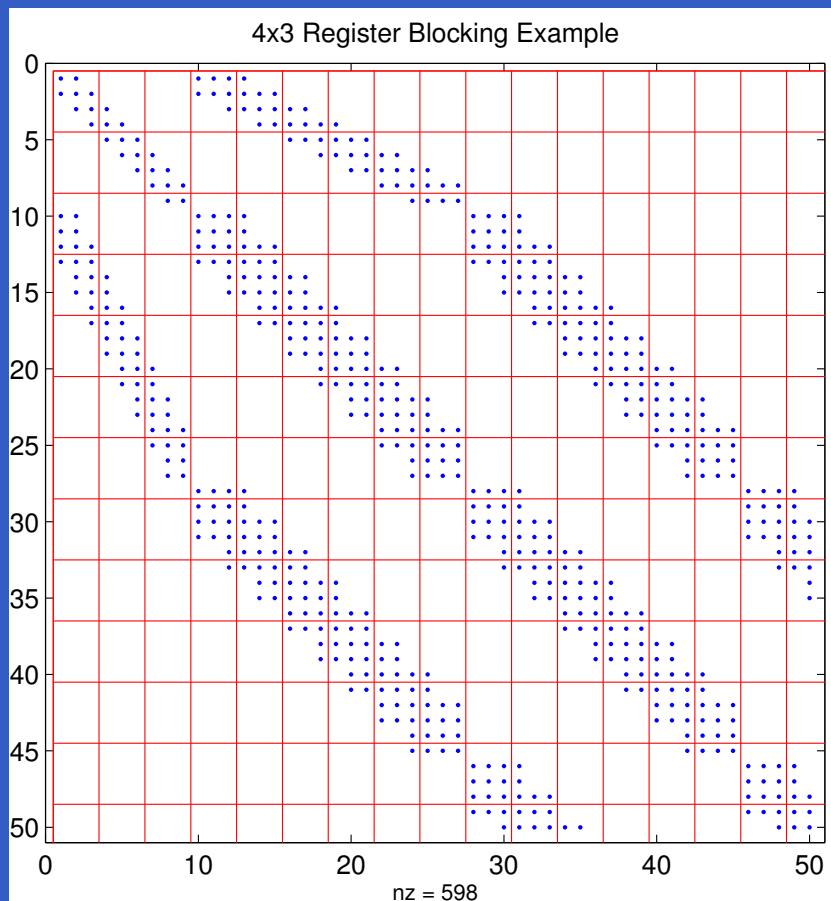
$$L_1 x_1 = y_1 \tag{1}$$

$$\hat{y}_2 = y_2 - L_2 x_1 \tag{2}$$

$$L_D x_2 = \hat{y}_2 \tag{3}$$

SPARSITY optimizations for (1)–(2); tuned BLAS for (3).

# Register Blocking (SPARSITY)



- Store  $r \times c$  dense blocks
- Multiply/solve block-by-block
- Fill in explicit zeros
- 1.3x–2.5x speedup on FEM matrices ( $\text{SpM} \times \text{V}$ )
- Reduced storage overhead over, e.g., CSR
- Block ops are fully unrolled – improves register reuse
- Trade-off extra computation for efficiency

# Tuning Parameter Selection

- Parameters: *switch point*,  $s$ , and *register block size*,  $b$
- Off-line profiling
  - Benchmark routines on synthetic data
  - Only needed *once* per architecture
- At run-time (when matrix is known)
  - Determine or estimate matrix properties (*e.g.*, fill ratio, size of trailing triangle)
  - Combine with data collected off-line
  - Convert to new data structure
- In practice, total run-time cost to select and reorg: *e.g.*, 10–30 naïve solves on Itanium

# Performance Bounds

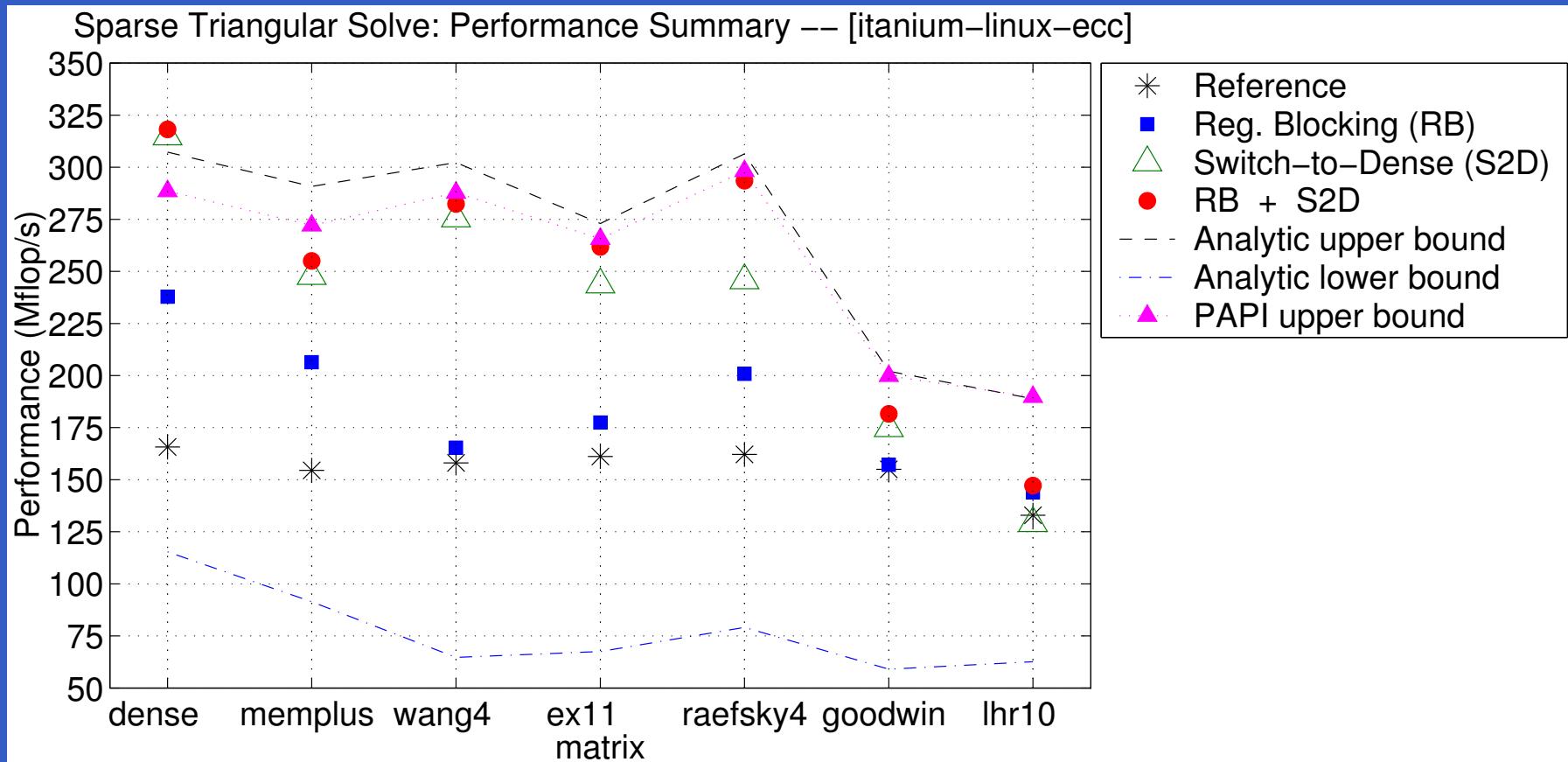
- *Upper-bounds* on performance (Mflop/s)?
- Flops:  $2 * (\text{number of non-zeros}) - (\text{dimension})$
- Full latency cost model of execution time:

$$T(s, b) = \sum_{i=1}^{\kappa-1} H_i(s, b)\alpha_i + M_\kappa(s, b)\alpha_{\text{mem}} \quad (4)$$

- Lower bound on misses: ignore conflict misses on vectors

$$M_{\text{lower}}^{(i)}(s, b) = \frac{1}{l_i} \left[ k f_b \left( 1 + \frac{1}{\gamma b^2} \right) + \frac{1}{\gamma} \left( \lceil \frac{n}{b} \rceil + 1 \right) + \left( 2n + \frac{(n-s)((n-s)+1)}{2} \right) \right] \quad (5)$$

# Performance Results: Intel Itanium



# Conclusions and Directions

- Limits of “low-level” tuning are near
  - Can we approach bandwidth limits?
  - Other kernels?  $A^T Ax$ ,  $A^k x$ ,  $RAR^T$
  - Other structures? multiple vectors, symmetry, reordering
- Interface from/to libraries and applications?
  - Leverage existing generators (e.g., Bernoulli)
  - Hybrid on-line, off-line optimizations
- SpTS-specific future work
  - symbolic structure; other fill-reducing orderings
  - refinements to switch point selection
  - Incomplete Cholesky and LU preconditioners

# Related Work (1/R)

- Automatic tuning systems
  - PHiPAC [BACD97], ATLAS [WPD01], SPARSITY [Im00]
  - FFTW [FJ98], SPIRAL [PSVM01], UHFFT [MMJ00]
  - MPI collective ops (Vadhiyar, *et al.* [VFD01])
- Code generation
  - FLAME [GGHvdG01]
  - Sparse compilers (Bik [BW99], Bernoulli [Sto97])
  - Generic programming (Blitz++ [Vel98], MTL [SL98], GMCL [Neu98], ...)
- Sparse performance modeling
  - Temam and Jalby [TJ92]
  - White and Sadayappan [WS97]
  - Navarro [NGLPJ96], Heras [HPDR99], Fraguela [FDZ99]

# Related Work (2/R)

- Compilers (analysis and models); run-time selection
  - CROPS (UCSD/Carter, Ferrante, *et al.*)
  - TUNE (Chatterjee, *et al.*)
  - Iterative compilation (O'Boyle, *et al.*, 1998)
  - Broadway (Guyer and Lin, '99)
  - Brewer ('95); ADAPT (Voss, 2000)
- Interfaces: Sparse BLAS; PSBLAS; PETSc
- Sparse triangular solve
  - SuperLU/MUMPS/SPOOLES/UMFPACK/PSPASES...
  - Approximation: Alvarado ('93); Raghavan ('98)
  - Scalability: Rothberg ('92; '95); Gupta ('95); Li, Coleman ('88)

—End—

# Tuning Parameter Selection

- First, select *switch point*,  $s$ ; at run-time:
  - Assume matrix in CSR format on input
  - Scan bottom row from diag. until two consecutive zeros found
  - Fill vs. efficiency trade-off
- Then, select *register block size*,  $b$ 
  - Maximize, over all  $b$ ,

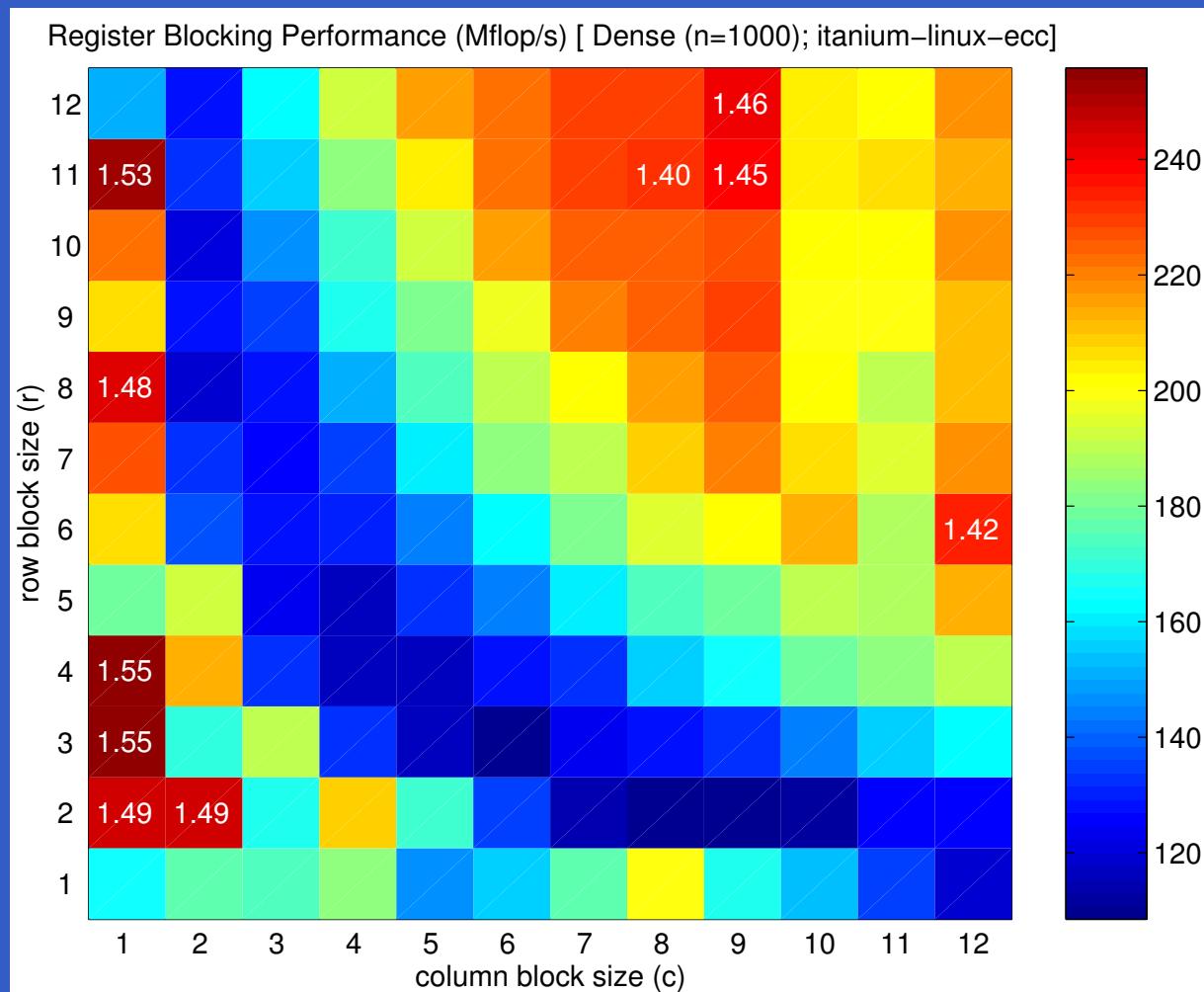
$$\frac{\text{Dense matrix in sparse format performance (Mflop/s) at } b}{\text{Estimated fill ratio at } b} \quad (6)$$

- Total cost to select and reorg.: *e.g.*, 10–30 naïve solves on Itanium

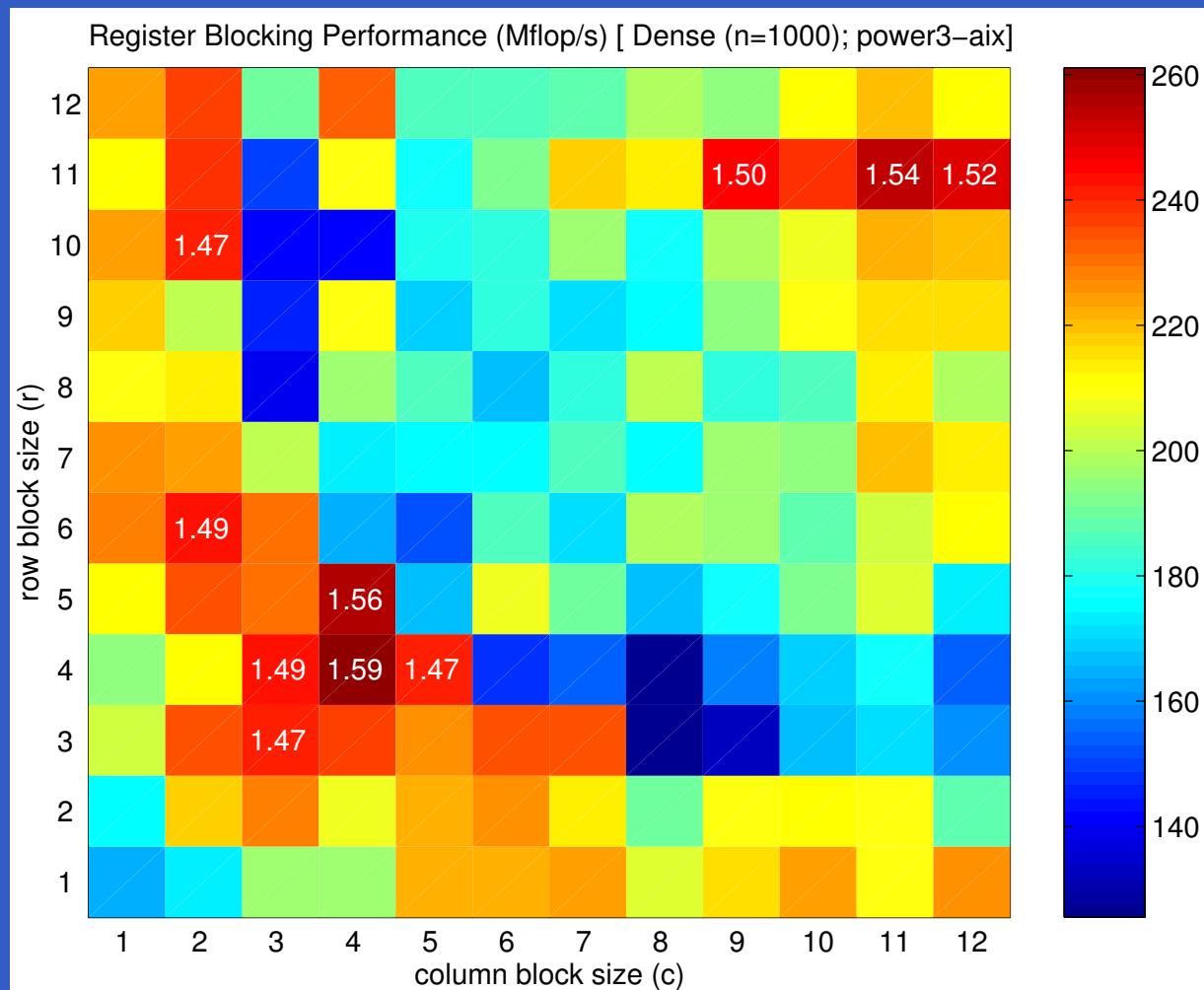
# Matrix Benchmark Suite

Name	Application Area	Dim.	Nnz in L	Dense	Trailing	Triangle	% Total Nnz
dense	Dense matrix	1000	500k	1000	100.0%	100.0%	
memplus	Circuit simulation	17758	2.0M	1978	97.7%	96.8%	
wang4	Device simulation	26068	15.1M	2810	95.0%	24.8%	
ex11	Fluid flow	16614	9.8M	2207	88.0%	22.0%	
raefsky4	Structural mechanics	19779	12.6M	2268	100.0%	20.4%	
goodwin	Fluid mechanics	7320	1.0M	456	65.9%	6.97%	
Ihr10	Chemical processes	10672	369k	104	96.3%	1.43%	

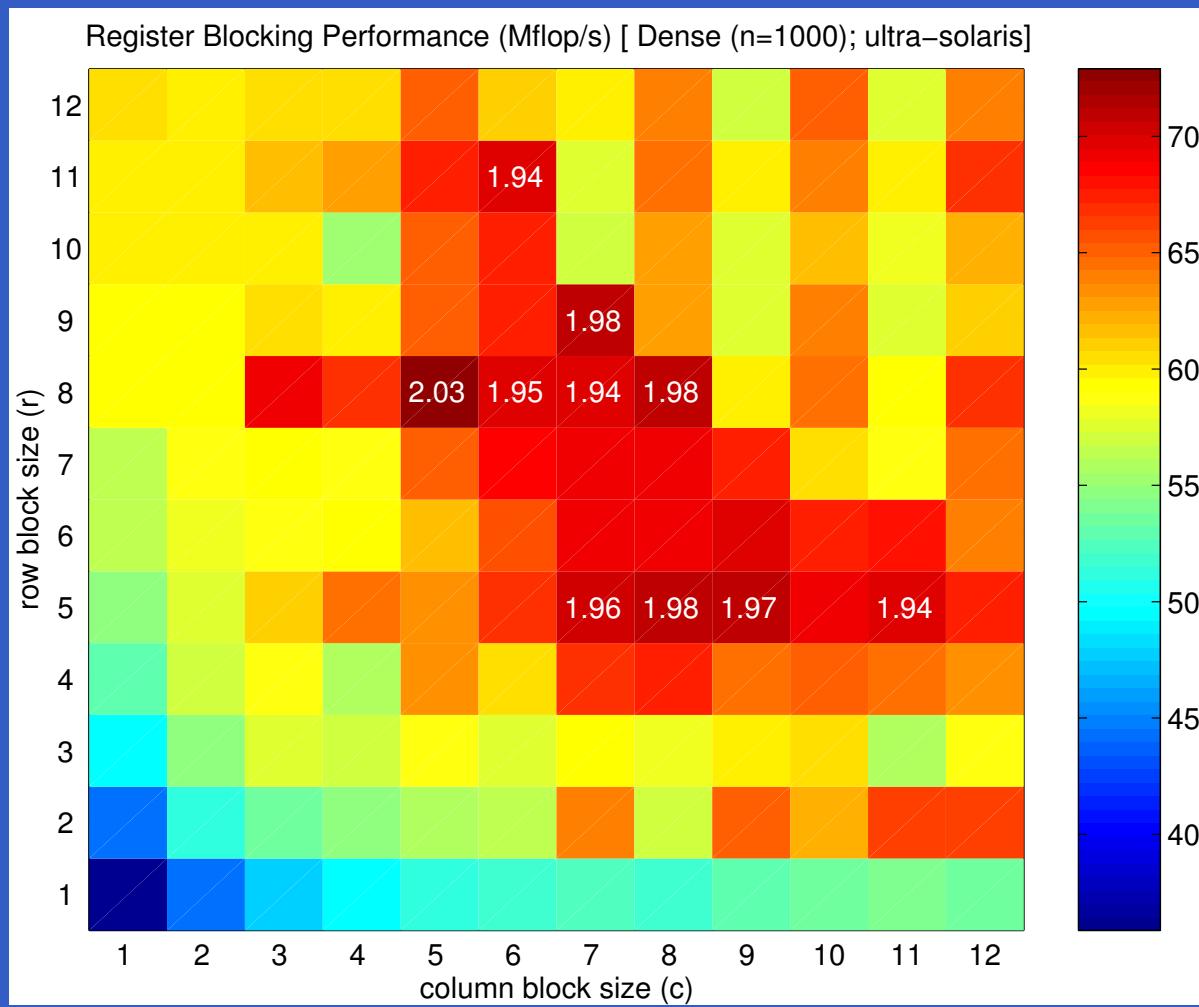
# Register Profile (Intel Itanium)



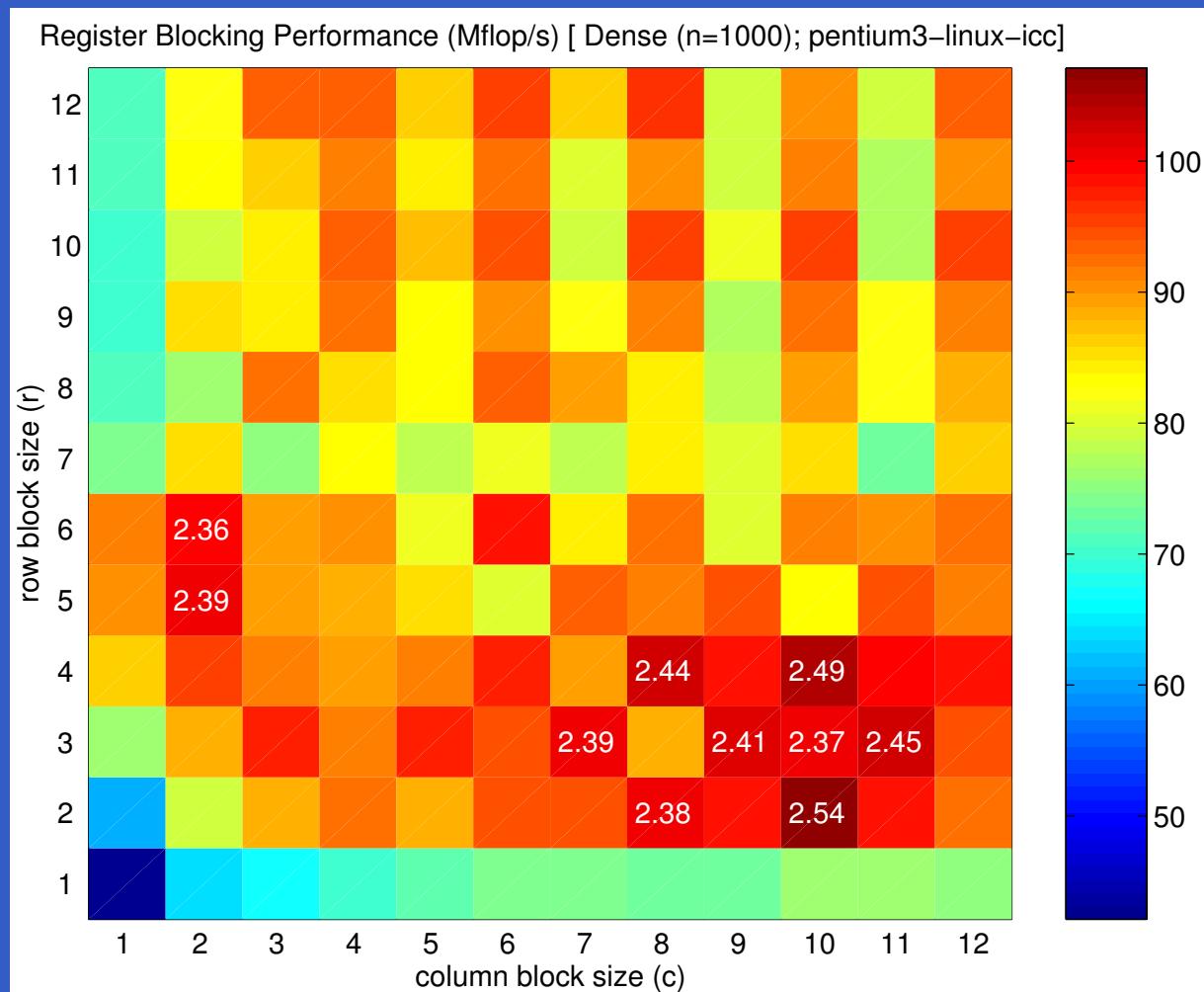
# Register Profile (IBM Power3)



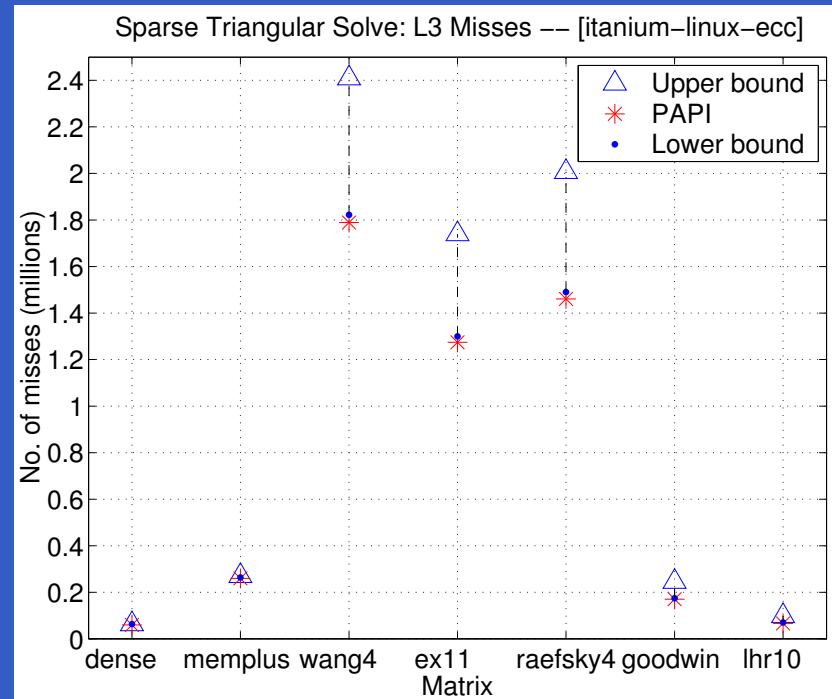
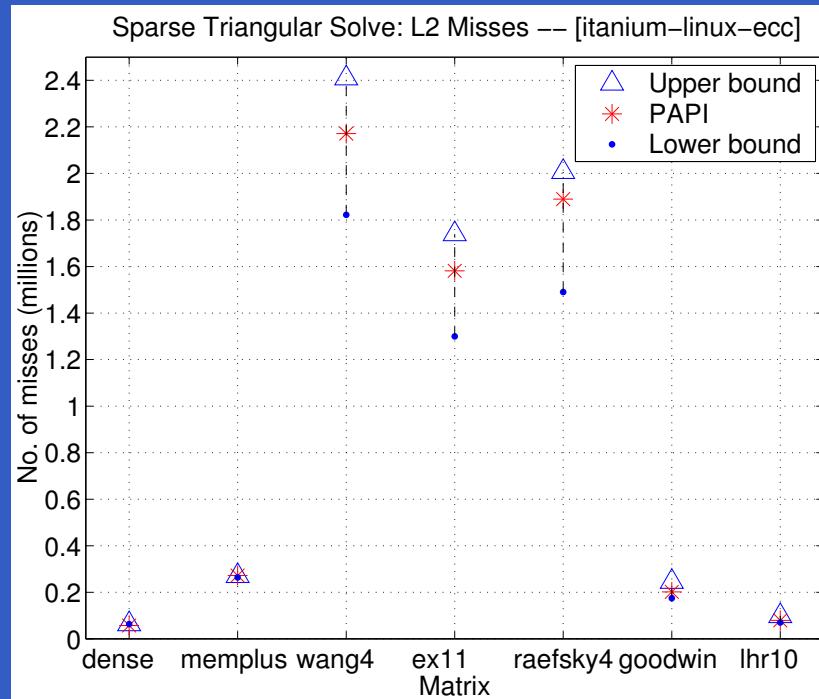
# Register Profile (Sun Ultra 2i)



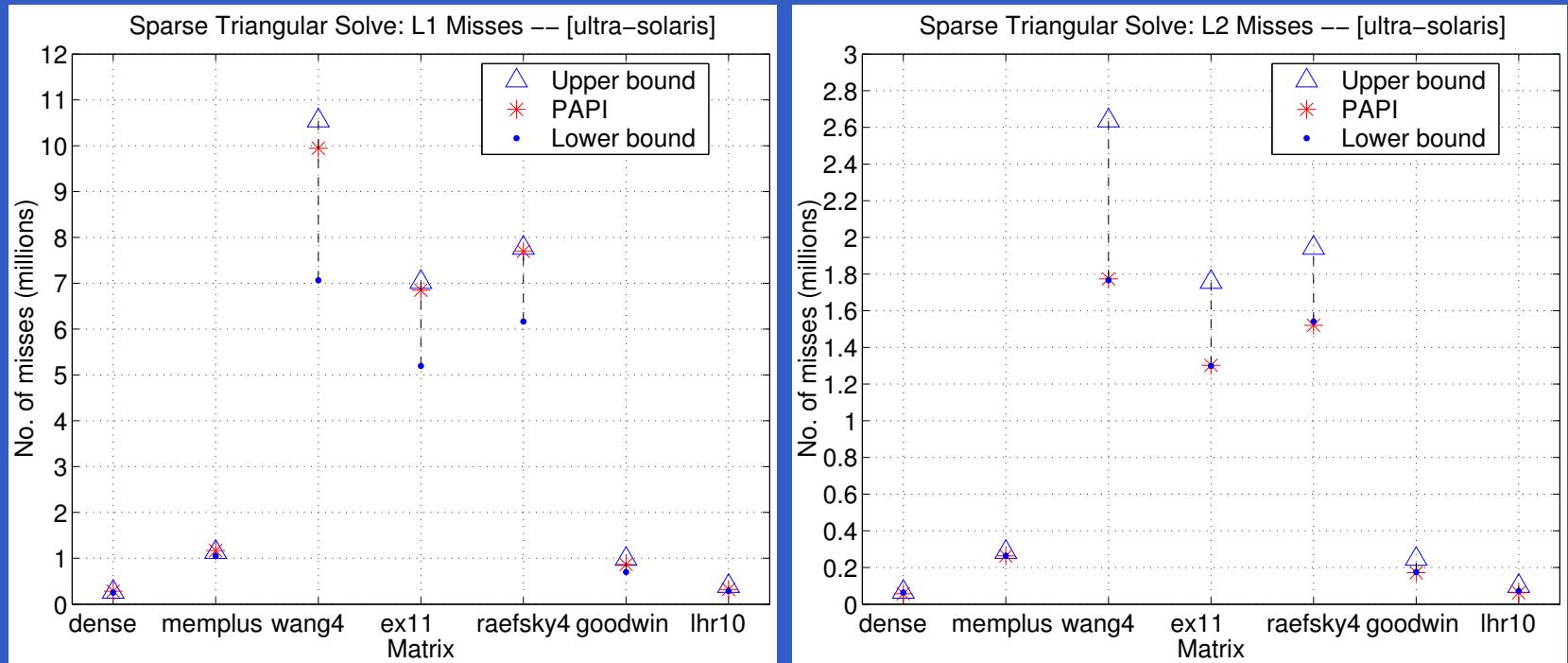
# Register Profile (Intel Pentium III)



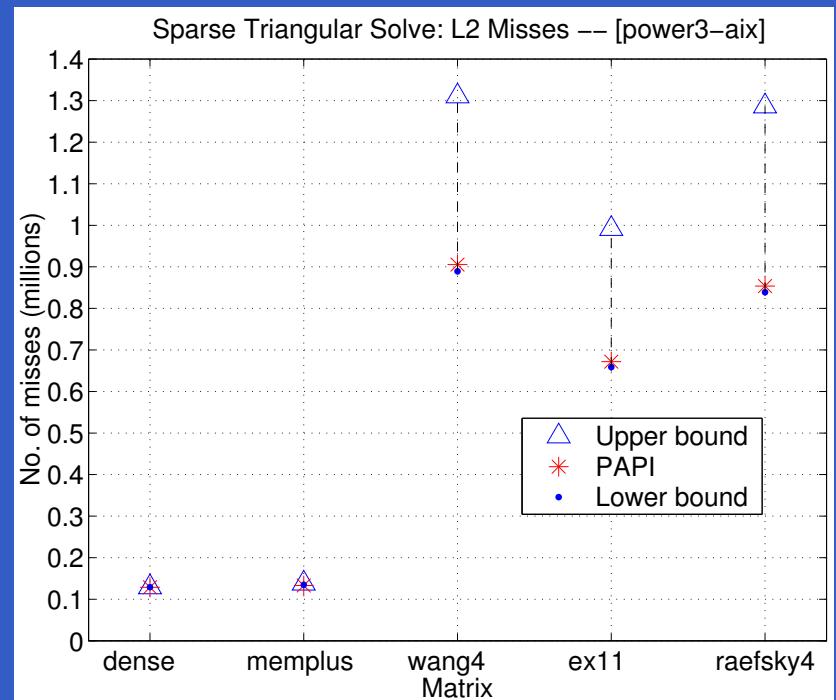
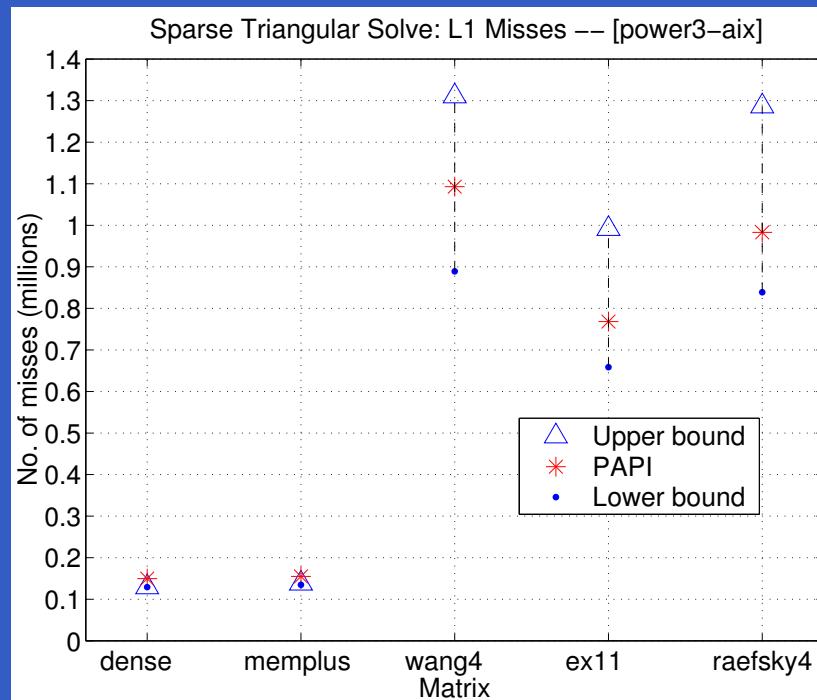
# Miss Model Validation: Intel Itanium



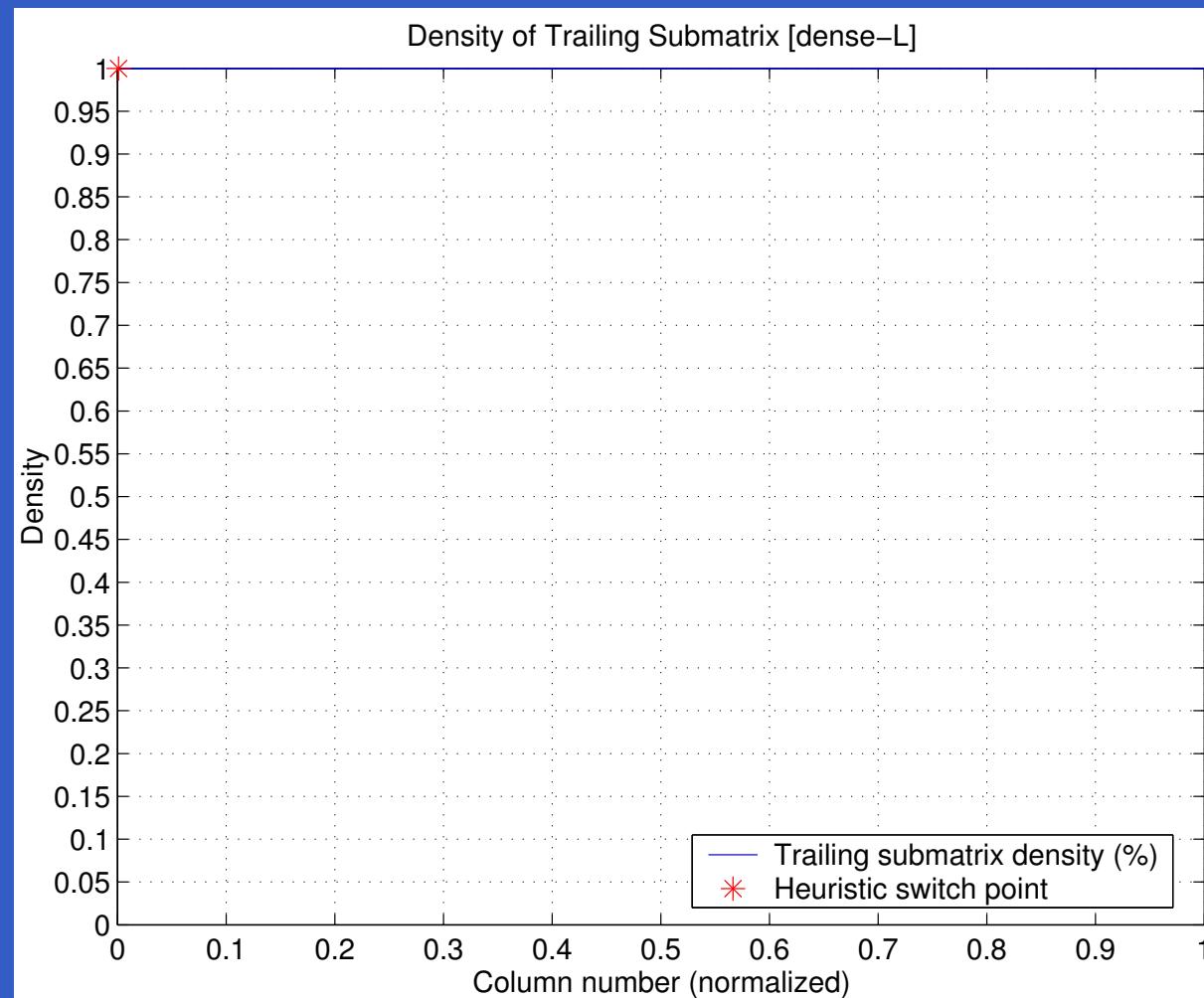
# Miss Model Validation: Sun Ultra 2i



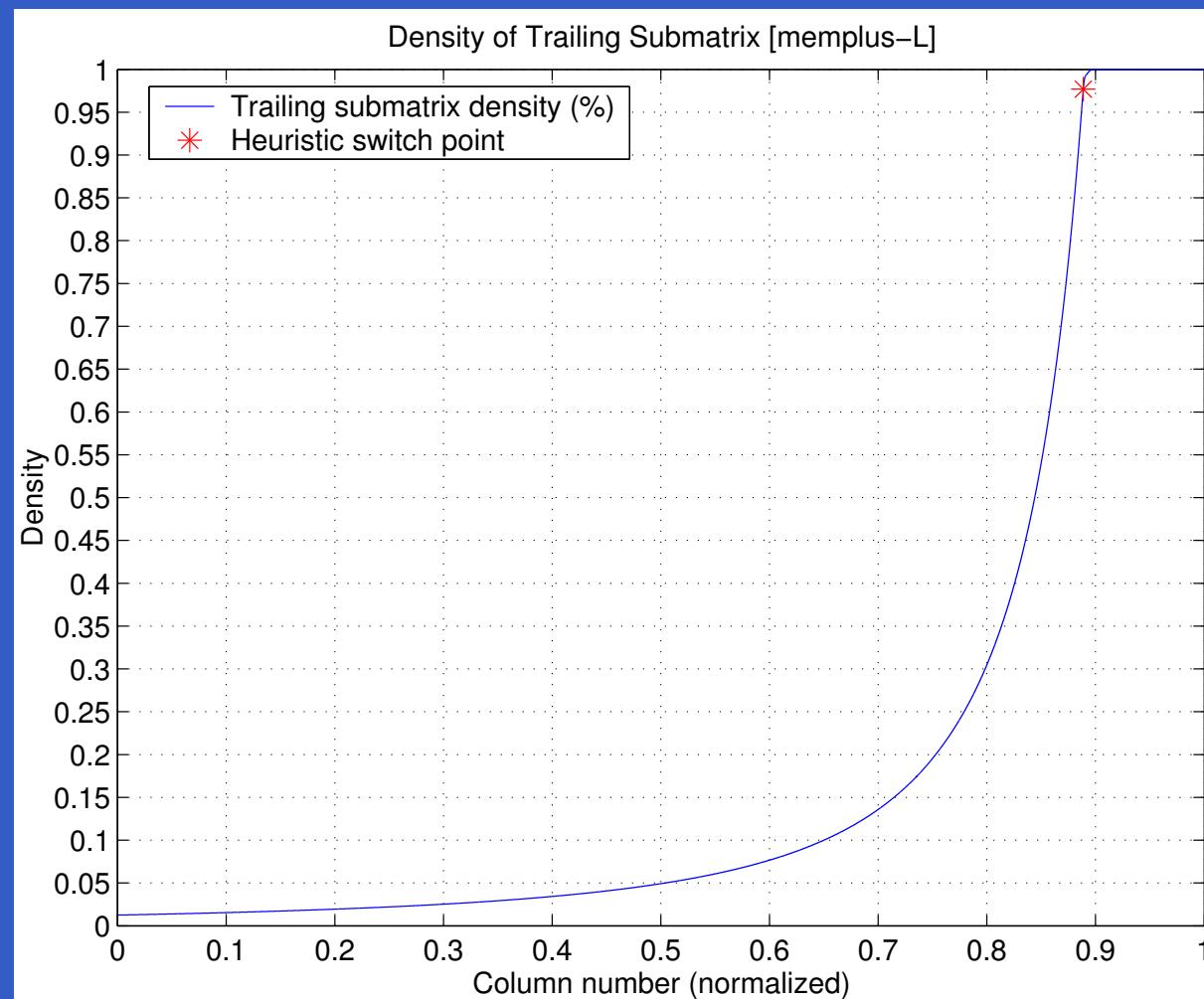
# Miss Model Validation: IBM Power3



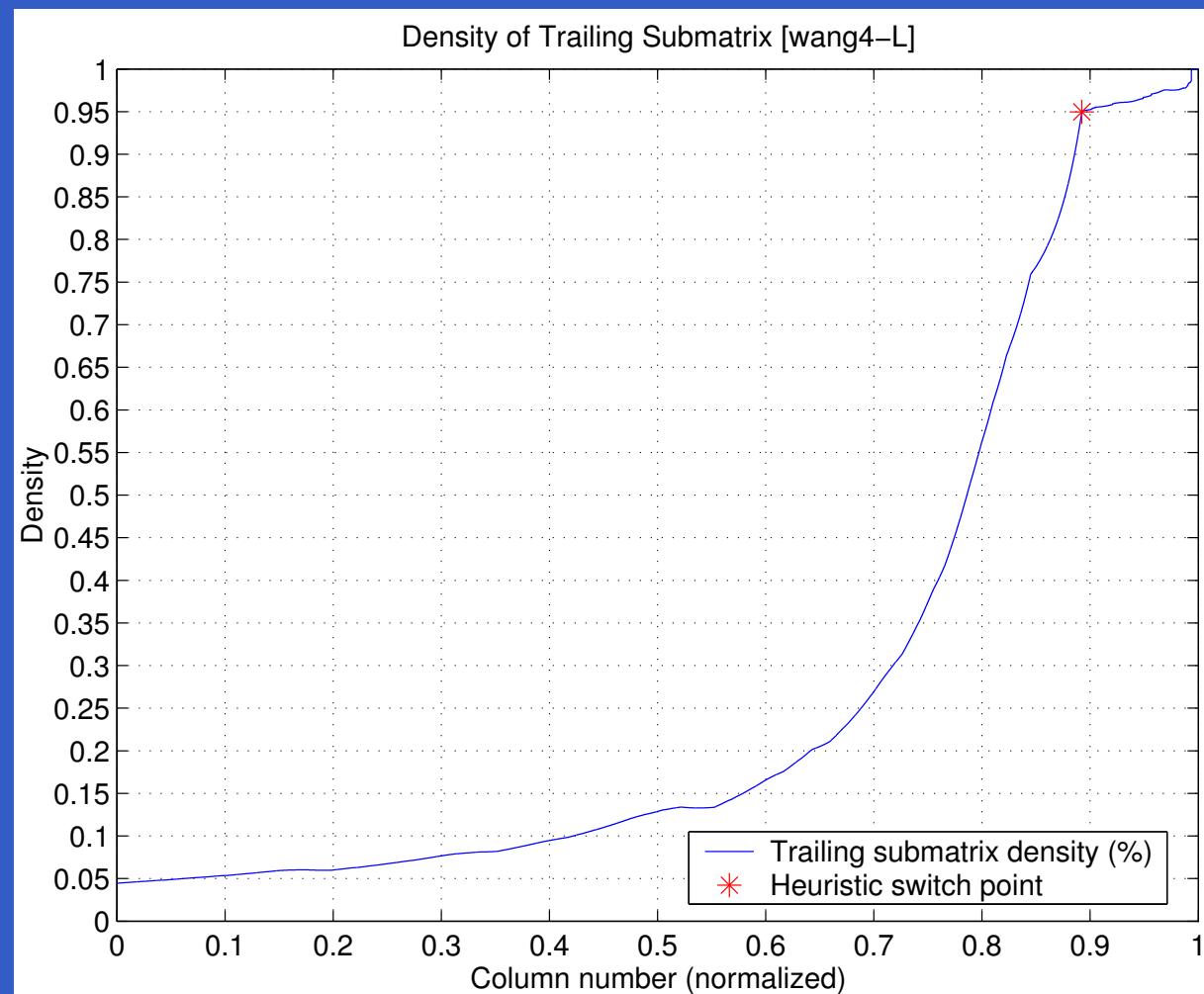
# Dense Triangle Density: Dense Matrix



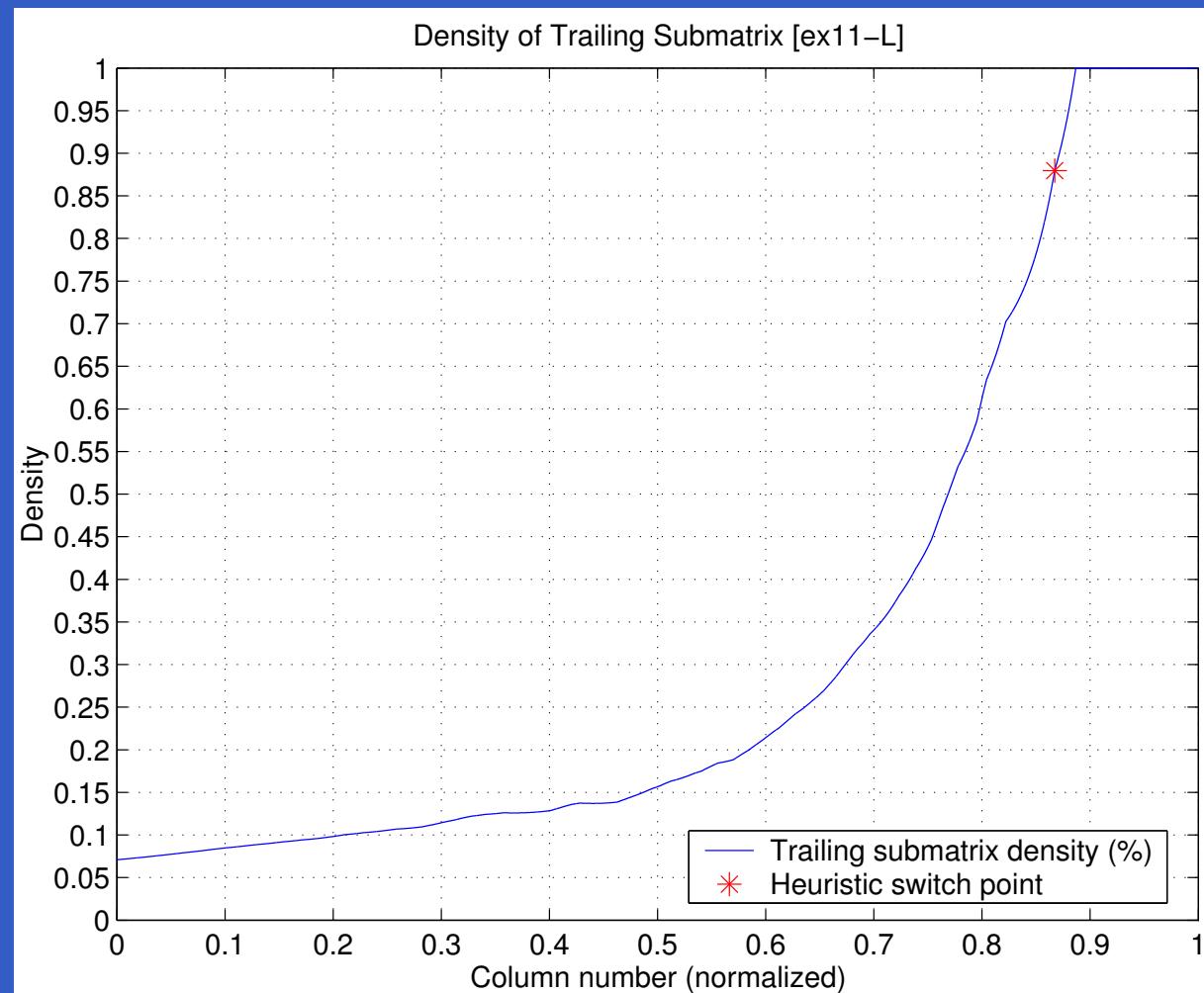
# Dense Triangle Density: memplus



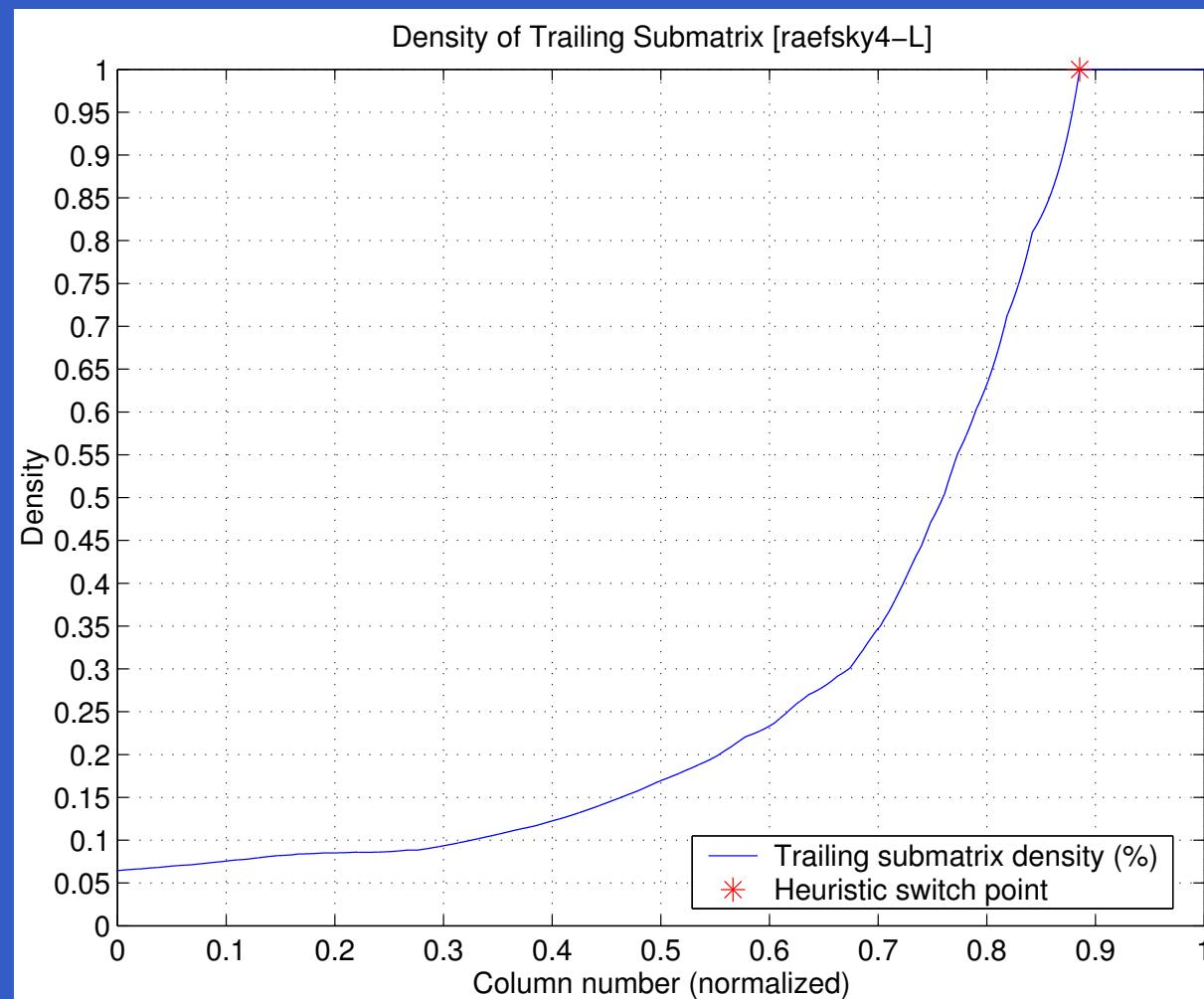
# Dense Triangle Density: wang4



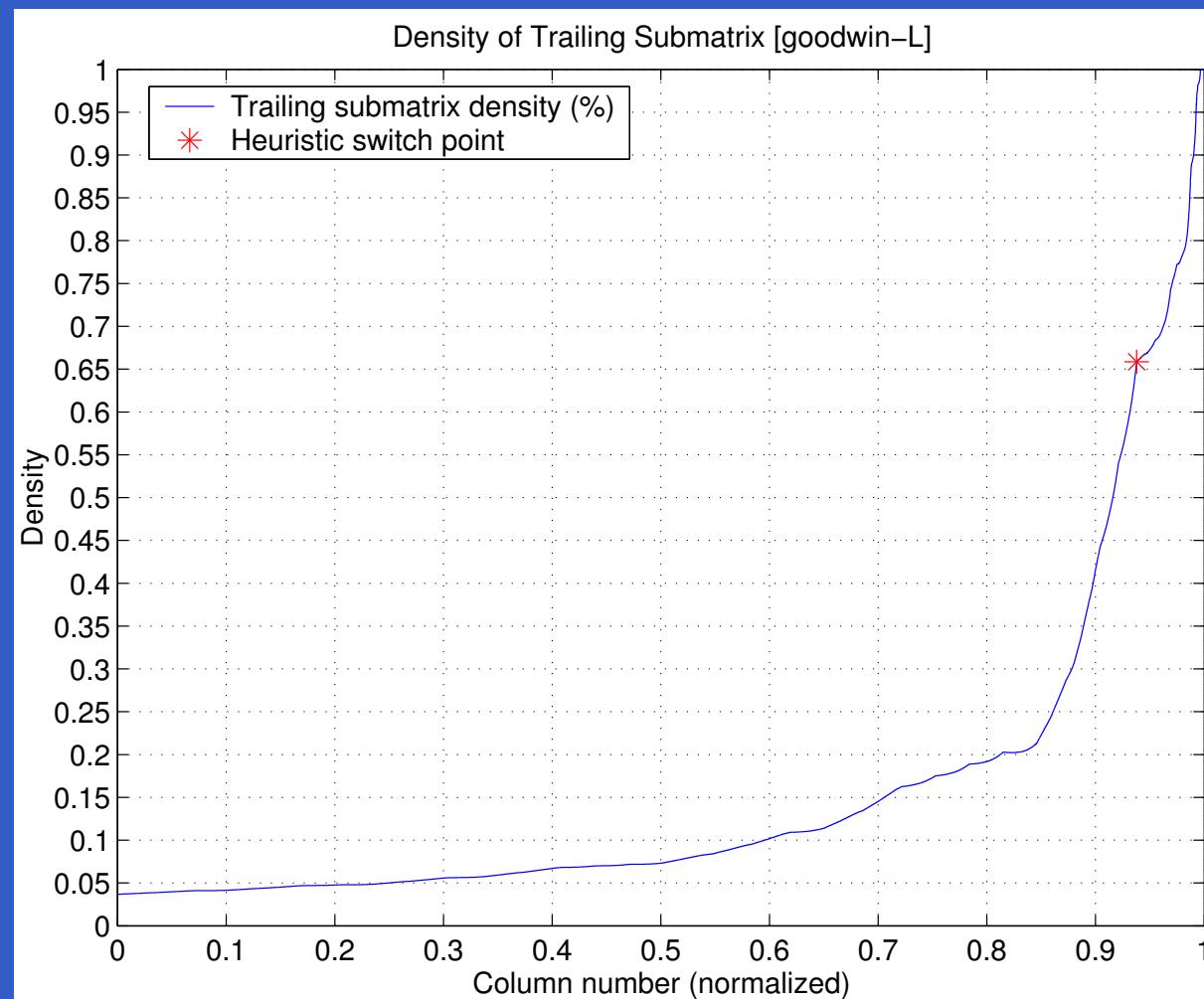
# Dense Triangle Density: ex11



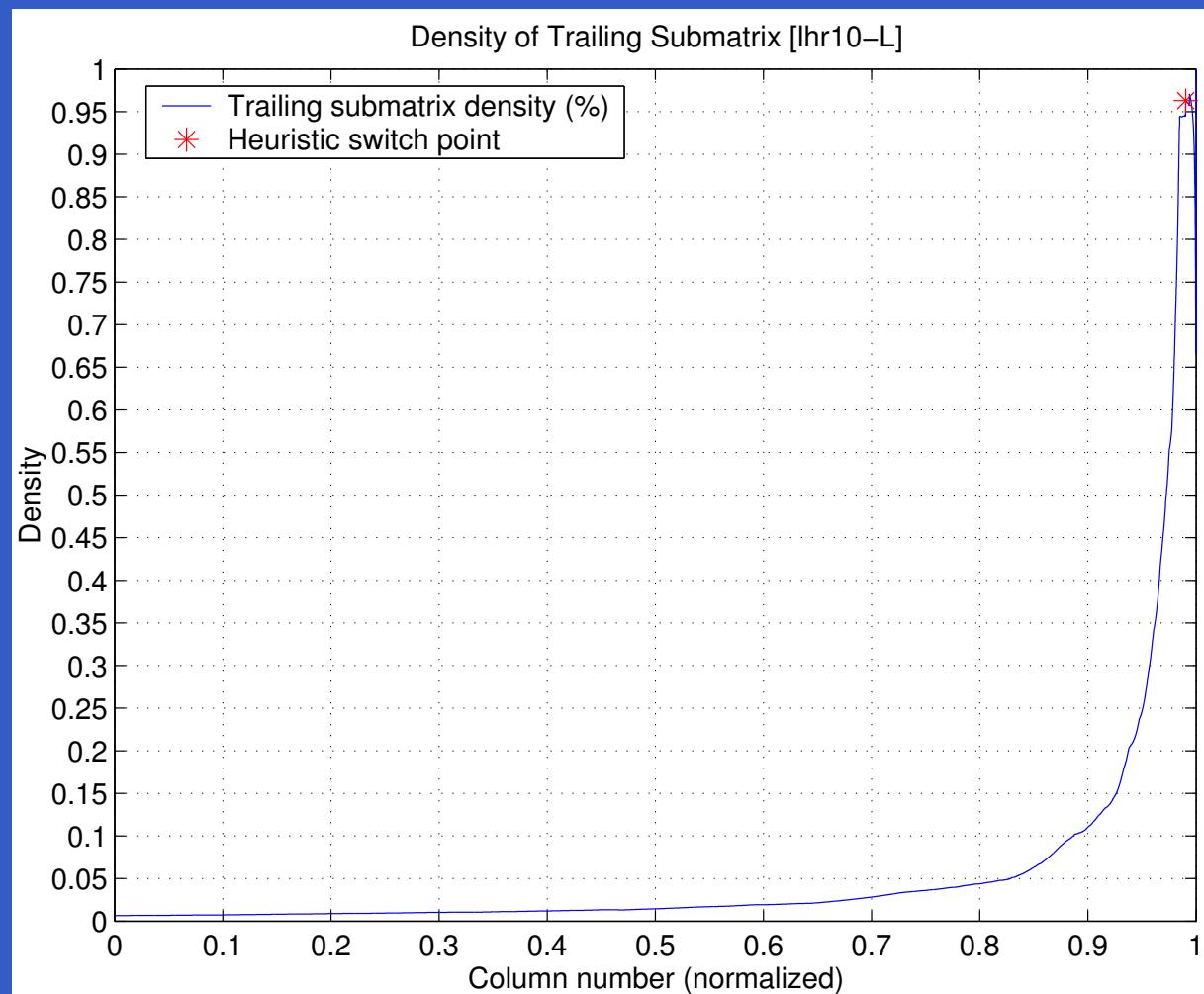
# Dense Triangle Density: `raefsky4`



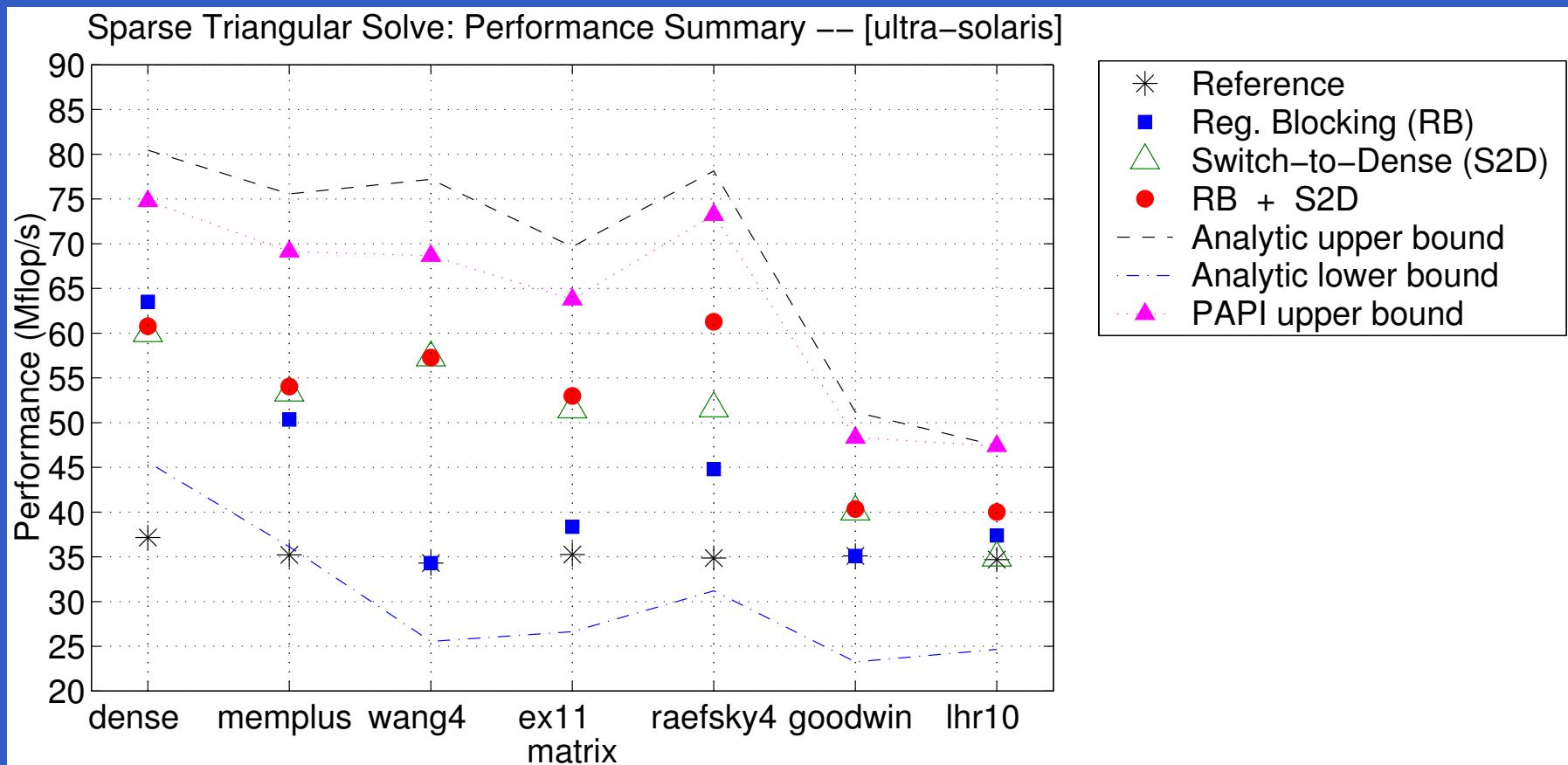
# Dense Triangle Density: goodwin



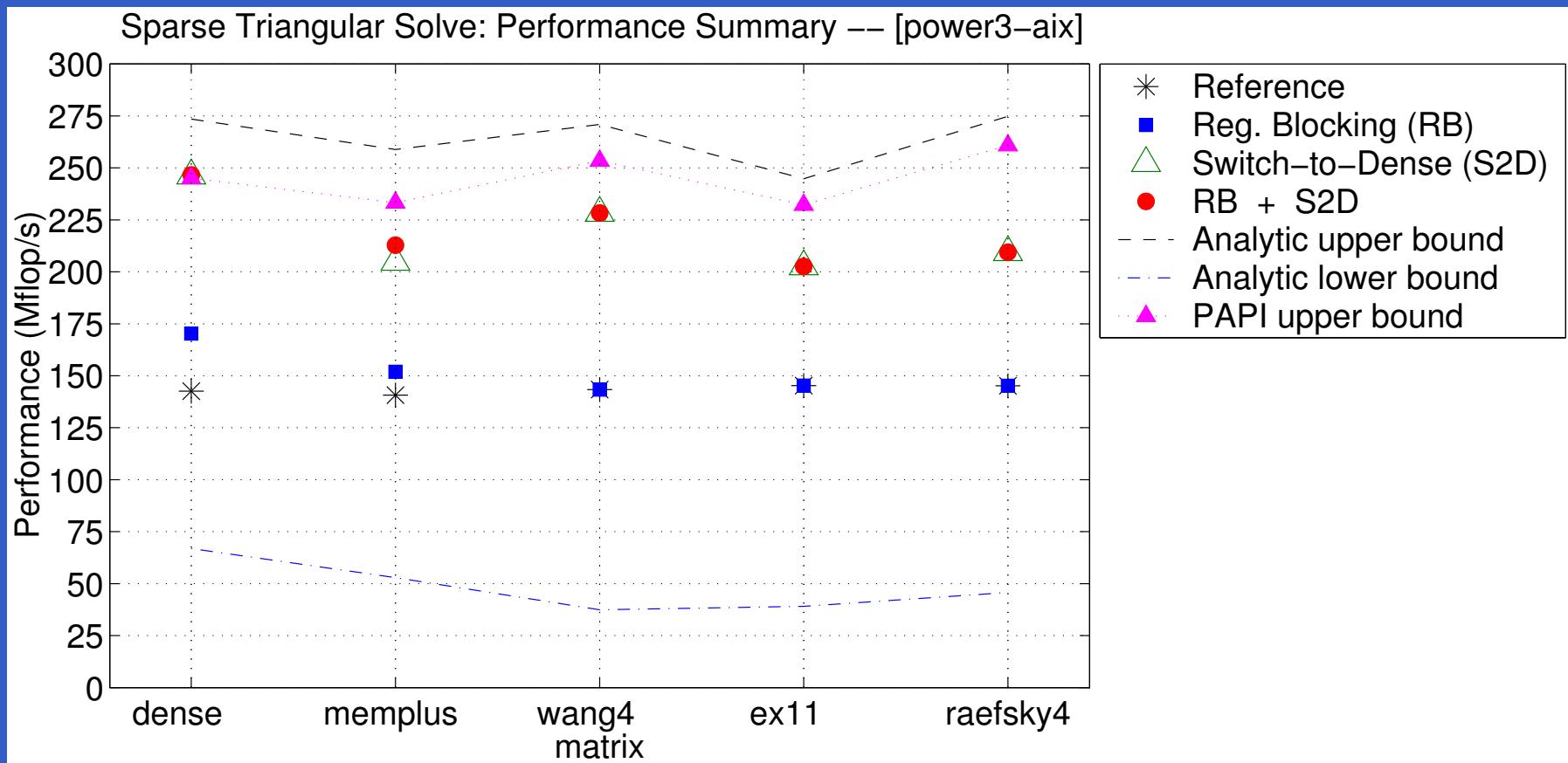
# Dense Triangle Density: `lhr10`



# Performance Results: Sun Ultra 2i



# Performance Results: IBM Power3



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